



Color constancy: Error evaluation based on angular error

Recovery error:







Angle-Retaining Chromaticity: color invariants and properties

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Computational Color Imaging Workshop

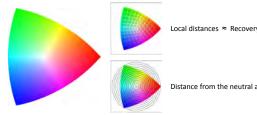
Reproduction error:

Angle-Retaining Chromaticity: color inv



$$\operatorname{err}_{\operatorname{rep}} = \operatorname{arccos}\left(\frac{\frac{i_{1}}{2} \cdot (1, 1, 1)}{|l_{1}^{\prime}| \sqrt{3}}\right) = \operatorname{arccos}\left(\frac{\sum}{\sqrt{\Sigma}}\right)$$

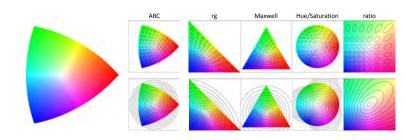
Angle-Retaining Chromaticity diagram



Local distances ≈ Recovery error

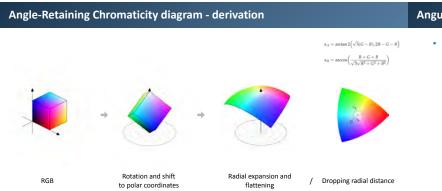
Distance from the neutral axis = Reproduction error

Angle-Retaining Chromaticity diagram



[1] M. Buzzelli, S. Bianco and R. Schettini. *ARC: Angle-Retaining Chromaticity diagram for color constancy error analysis.* JOSA A 37.11 (2020): 1721-1730. naticity: color invariants and properties

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T. Chen, Z. Deng and J. Ma. "A spherical perceptual color model." Color Imaging XVIII: Displaying, Processing, Hardcopy, and Applications. Vol. 8652. SPIE, 2013.

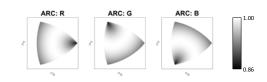
Angular distance vs. Euclidean distance

• If I change the input RGB by a certain amount,

how much does the angular distance in RGB change?

how much does the euclidean distance in ARC change? _

ang_dist([R G B]☉δ, [R G B]☉δ) euc_dist(ARC([R G B]⊕δ), ARC([R G B]⊖δ))

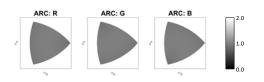


5 Angle-Retaining Chromaticity: color invariants and properties

Angular distance vs. Euclidean distance

- If I change the input RGB by a certain amount,
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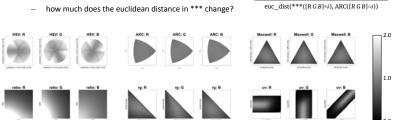
ang_dist([R G B]⊕δ, [R G B]⊝δ) $euc_dist(ARC([R G B] \circ \delta), ARC([R G B] \circ \delta))$



Normalized with a common scale s.t. the center of the diagram is 1:1

Angular distance vs. Euclidean distance

- If I change the input RGB by a certain amount,
 - how much does the angular distance in RGB change? how much does the euclidean distance in *** change?



ang_dist([R G B]⊙δ, [R G B]⊙δ)

 Concentric spheres in RGB -> Equal-sized horizontal planes in ARC Low-intensity RGB

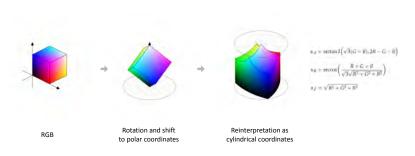
· Rays from the origin in RGB -> Parallel vertical lines in ARC

triplets stretched out

to span the same area of high-intensity ones

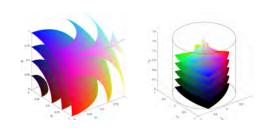
Normalized with a common scale s.t. the center of each diagram is 1:1

Angle-Retaining Color space - derivation



[3] M. Buzzelli, S. Bianco, R. Schettini, "Angle-Retaining Color Space for Color Data Visualization and Analysis". In Proceedings of the International Colour Association (AIC) Conference 2021. Milan, Italy, AIC, pp. 245-250, 2021.

RGB gamut in ARC space



[3] M. Buzzelli, S. Blanco, R. Schettini. "Angle-Retaining Color Space for Color Data Visualization and Analysis". In Proceedings of the International Colour Associa Conference 2021. Milan, Italy. AIC, pp. 245-250, 2021.

Color invariants of ARC space components

• Which ARC components are invariant to which color transformations [4] ?

	Light intensity change	Light intensity shift	Light intensity change and shift	Light color change	Light color change and shift
	$\begin{pmatrix} a & 0 & 0 \\ 0 & a & 0 \\ 0 & 0 & a \end{pmatrix} \begin{pmatrix} R \\ G \\ B \end{pmatrix}$	$\begin{pmatrix} R \\ G \\ B \end{pmatrix} + \begin{pmatrix} o_1 \\ o_2 \\ o_1 \end{pmatrix}$	$\begin{pmatrix} a & 0 & 0 \\ 0 & a & 0 \\ 0 & 0 & a \end{pmatrix} \begin{pmatrix} R \\ G \\ B \end{pmatrix} + \begin{pmatrix} o_1 \\ o_1 \\ o_1 \end{pmatrix}$	$\begin{pmatrix} a & 0 & 0 \\ 0 & b & 0 \\ 0 & 0 & c \end{pmatrix} \begin{pmatrix} R \\ G \\ B \end{pmatrix}$	$\begin{pmatrix} a & 0 & 0 \\ 0 & b & 0 \\ 0 & 0 & c \end{pmatrix} \begin{pmatrix} R \\ G \\ B \end{pmatrix} + \begin{pmatrix} o_1 \\ o_2 \\ o_3 \end{pmatrix}$
a _A (Hue)	Invariant	Invariant	Invariant	Not invariant	Not invariant
$a_{\rm g}$ (Saturation)	Invariant	Not invariant	Not invariant	Not invariant	Not invariant
$a_{\rm Z}$ (Intensity)	Not invariant	Not invariant	Not invariant	Not invariant	Not invariant
	Shadows and shading (no-colored lighting geometry changes)	Diffuse lighting, object highlights, interreflections, infrared sensitivity		Change in illuminant color, light scattering (von Kries)	Increased diffuse light

[4] K. van de Sande, T. Gevers and C. Snoek, "Evaluating Color Descriptors for Object and Scene Recognition," in IEEE Transactions on Pattern Analysis and Machine Intelligence, vol. 32, no. 9, pp. 1582-1596, Sept. 2010, doi: 10.1109/TPAMI.2009.154.

Potential for application

Color constancy .

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- A color space that encodes angular distances as Euclidean distances
- Implicitly provides a sensitivity to angular target metrics.
- Facilitates optimization process for illuminant estimation methods.
- Texture analysis
 - Inclusion of color-aware descriptors in traditional LBP texture descriptors
 - Improves image classification under varying illuminant conditions
 - Other descriptors potentially enhanced with color-invariant properties
- Image denoising and enhancement
- Separation of image data into color-related and intensity-related components
 - Successfully applied for image denoising and enhancement
 - Potential benefit in applications where the illuminant characterization should be preserved

